



# PSLV-C26/IRNSS-IC



# PSLV-C26



20LV-C24 to First Lewisch Fool

Polor Satellite Latinch Vehicle, in its twenty eighth flight (PSLV-C26), will hancit IRNSS-IC, the third satellite of the Indian Regional Navigation Satellite System (IRNSS). The launch will take place from the Parst Launch Pad (FLP) of Satish Dhawan Space Centre (SDSC) SHAR, Sribarikota. PSLV-C26 will tase 'XL' version of PSLV. This is the seventh time 'XL' configuration is being flown, earlier six being PSLV-C11/Chandrayaan-I, PSLV-C17/OSAT-12, PSLV-C19/RISAT-1, PSLV-C22/IRNSS-1A, PSLV-C25/Mars-Orbiter Spacecraft and PSLV-C24/IRNSS-IB missions.

## PSLV-C26 at a glance with a little throat mass 320 tonno. Height 44 4 mg

	hoged	Mog-E	Stope-7	Magazi
Magnenciature	Com Stage PST + & Strap-on Motors	P5:2	<b>₹</b> \$3	PSa .
Propedient	Solid (HTPS borad)	Ugud (UH25 + NÇO),	Solid [HTP8 bosed]	bupid  MWM = MONIA
Mose (7)	138.2 (Core). 6 x 12.2 (Strop-on)	42.0	7.6	2,5
Mice Trivial (RdV)	4819 (Coro), 6 x 710 (Strep-ce)	B94	240	7.3 x 2
Stage Silo (m)	2.8 (Care),   {Strap-on}	2,0	2.0	2,6
Brose Length (m)	20  Corej,   2  Shapen]	12.8	7.6	3.0

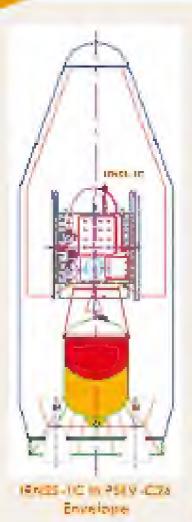
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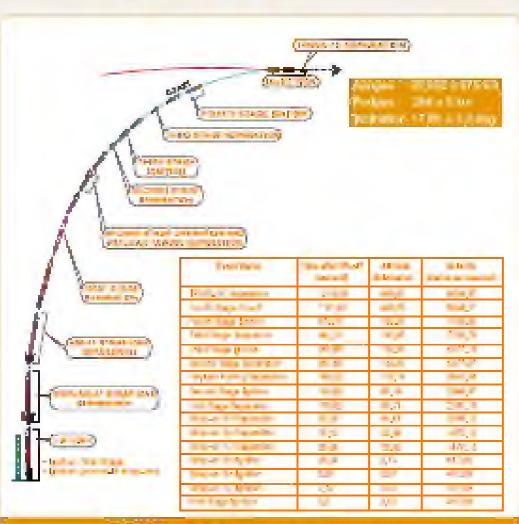
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# PSLV-C26





PSLV-C26 Typical Flight Profile



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# IRNSS-1C

IRNSS-IC is the third navigation satellite of the seven satellites constituting the IRNSS space segment. Its predecessors, IRNSS-IA and IRNSS-IB were launched by PSLV-C22 and PSLV-C24 in July 2013 and April 2014 respectively. IRNSS-IC has a lift-off mass of 1425.4 kg. The configuration of IRNSS-IC is similar to that of IRNSS-IA and IRNSS-IB. The satellite has been realised in less than six months after the launch of mappredecessor.

The two solar panels of IRNSS-IC copasiting of Ultra
Triple Junction solar cells generate about 1660
Water of electrical power, Sun and Star sensors
as well as gyroscopes provide orientation
beference for the tatellite. Special thermal
control schemes have been designed
and implemented for some of the
critical elements such as atomic
clocks. The Attitude and Orbis
Control System (AOCS) of IRNSS IC
maintains the satellite's orientation with
the help of reaction wheels, magnetic sompten
and thrusters, its propulation system consists of a
Leguid Apogee Motor (LAM) and thrusters.

(ERLI-IC spacecraft undergoing Elecha-Magella Introference and Bectio-Magella Corporability (EM) EMC) tests

IRNSS-IC will be launched (non a sub-Georynchronous Transfer Orbit (sub-GTO) with a 284 km perigee (nearest point to Earth) and 20,650 km apogee (farthest point to Earth) with an inclination of 12.86 deg with respect to the equatorial plane.

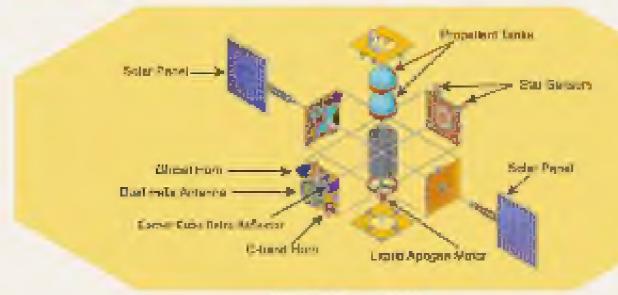
After injection into this preliminary orbit, the two solar panels of IRNSS-IC are automatically deployed in quick succession and the Master Control Facility (MCF) at Hassan takes control of the satellite and performs the initial orbit raising manocurres consisting of one manocurre at perigee (nearest point to earth) and three at apages (farthest point to earth). For these manocurres, the Liquid Apoges Motor (LAM) of the satellite is used, thereby finally placing it in the circular geostationary orbit at its designated location.

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lintss-1 Capacer of being exempled with PT-VC-3V

#### IRNSS-1C Sallent features

ОВВП	Geostalionary, at 83 deg East langitude	
LIFT-OFF MASS	1425.4 kg	
DRY MASS	600.1 kg	
PHYSICAL DIMENSIONS	1.58 metro x 1.50 metro x 1.30 metro	
POWER	1wo yakr panels generating 1660 W, one Lithium-ion battery of 90 Ampero-Hour capacity	
PROPULSION	440 Newton Liquid Apagee Malar, twoke 22 Newton Ihrusters	
CONTROL SYSTEM	Serp momentum system, attentation input from Sun & Stat Serson and Gyroscopes. Reaction Wheels, Magnetic Torques and 22 Newton thrusten as actuators	
MIESION LIFE	10 years	



DESCRIPTION OF PERSONS ASSESSED.

#### PAYLOADS:

IRNSS-IC carries two types of psyloods - navigation psylond and ranging psylond. The cavigation psylond of IRNSS/IC will cransmit navigation psylond of IRNSS/IC will cransmit navigation, service signals to the users. This podes distribute operating in 1.1 hand (1176.4) MHz) and 5 hand (2492,028 MHz). A highly accorate Robotium assente chack to part of the navigation psylond of the satellite. The tenging psylond of IRNSS-IC consults of a Chand transponder which facilitates accumite determination of the range of the smellite IRNSS-IC also carries Curves Cube Retro Robotium for lower ranging.



### IRNSS Overview:

IBNSS is an independent regional transport of stellar system being developed by India. It is designed to provide accurate position information wrenty in users to India as well as the region extending up to 1500 km Inors as instanlary, which is the property service area and area enclared by the restangle from Lagrande 30 deg South to 50 deg North, Longitude 50 deg Basers 110 deg East.

ISMS5 will provide non types of services, namely. Standard Positioning Service ISPS; which is provided to all the users and Restricted Service (RS), which is an entrypted service provided only to the authorised ones. The (RNSS Speem to expected to provide a position accuracy of better than 20 to in the primary needs area.

IBNSS comprise of a space segment and a ground regiment. The IRNSS space segment consists of seven smallites, with three ascellites in programmary urbu and form smallites in inclined gensynthmanus orbin. IRNSS-IA and IRNSS-IB, the first own smallites of the IRNSS constellation, have should started fitteetiming than their designated orbits also after extensive on orbit segment evaluation of confirm their satisfactors performance.

18/N55 ground regress to responsible for newtonion parameter peneration and (neutrosition, swelline countril, ranging and integray mentaging a yell as time keeping.

#### the constituent elements of the IBNSS ground tegment are:

 ESRO Novigation Centre (INC) at Byalalu, is the nerve center of the JRNSS Ground Segment, INC primarily generates natingation parameters.

- (RMSS Rang) and Emergity Microwering Storage (IREMS) perform continuous one way ranging of the IROSS satesiates and are also used the totograpy determinant of the IRMSS assets for account.
- TRASS CDMA Banging Enterto (IRCDR) carevious process two way stagging of IRNSS sets form.
- Bydale generates, maintains and distributes BUNSS.
  Network Time
- Special Costrol Fields (CCF) statute the space regiment fluorigh Telesconv Tracking & Command networks in addition to the regular TTSC operation, IRSCF also optimis the companion parameters processed by the INC.

IRMS Flata Communication Network (IR/OCN) prevales the required digital economication buildrane to IROSS helbonic

Intercettimal Later Ranging Stations (ILES) is being used periodically a publicate the LENSE or to determined by the other techniques.



#### Applications of IRNSS:

- · Norresma, Arma and Marine Navananan.
- Vehicle tracking and fleet management.
- · Procure Timing
- · Tertestrial mavigation and fire history and tratellers.
- Disason Manapoissont.
- \* Integration with maloic phones
- Mapping and Condette data captum.
- · Visited and since testigations for drivers



#### Indian Space Research Organisation

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